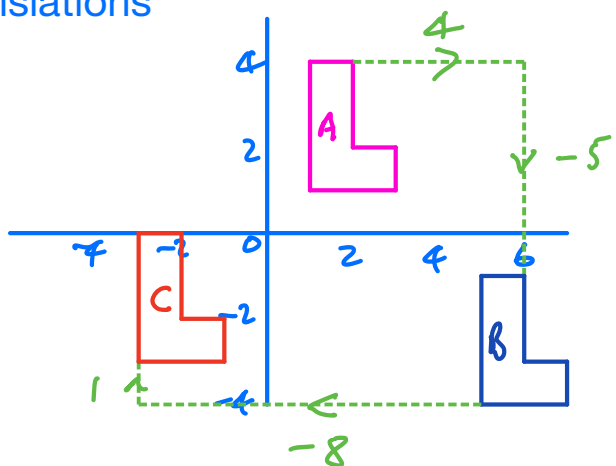


Transformations - Translations, Reflections, Rotations, Enlargements

Translations



Translate A by $\begin{pmatrix} 4 \\ -5 \end{pmatrix}$ to give B

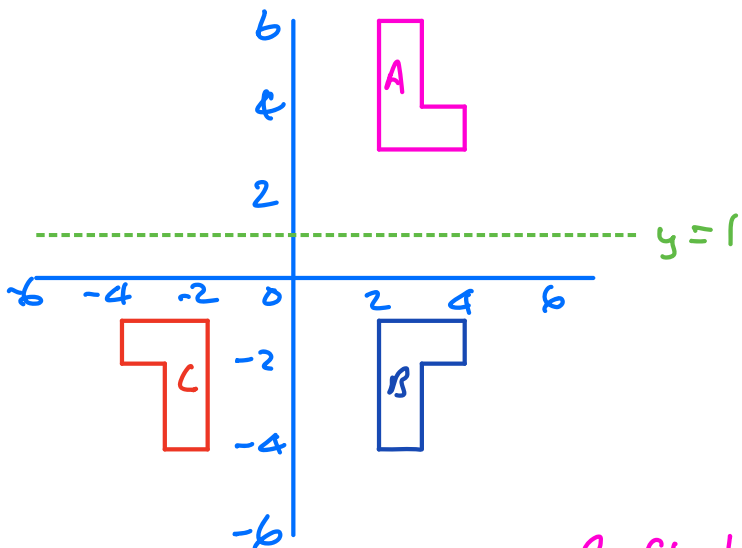
Translate B by $\begin{pmatrix} -8 \\ 1 \end{pmatrix}$ to give C

Describe the transformation required to map C back to A.

Translate by $\begin{pmatrix} 4 \\ 4 \end{pmatrix}$

Translate by $\begin{pmatrix} x \\ y \end{pmatrix}$ means move x in the x -direction and y in the y -direction. It is called a column vector.

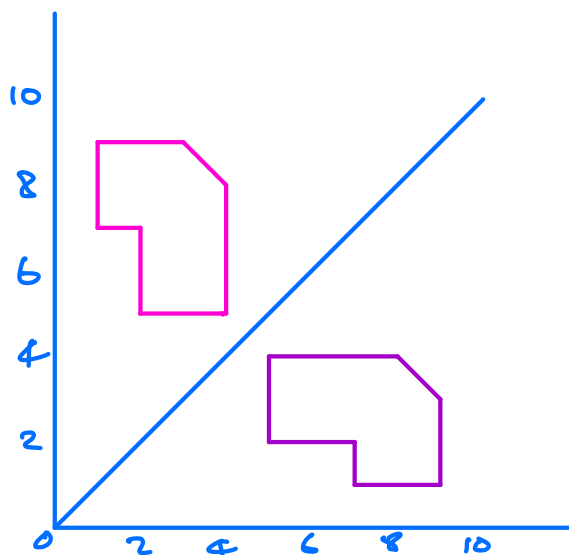
Reflections



Reflect A in line $y=1$ to give B

Reflect B in y -axis to give C

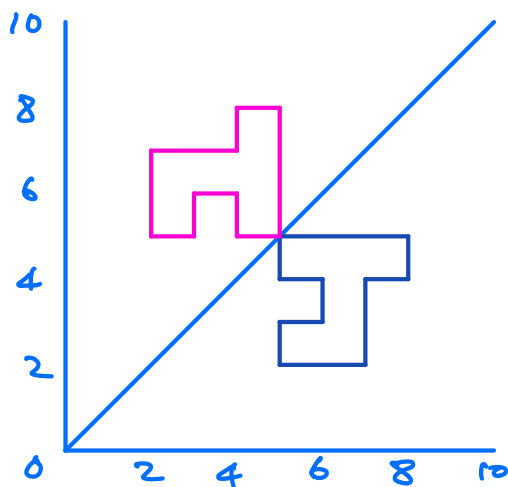
Reflect in Line $y=x$
 $(x, y) \rightarrow (y, x)$



For each point the coordinates are reversed.

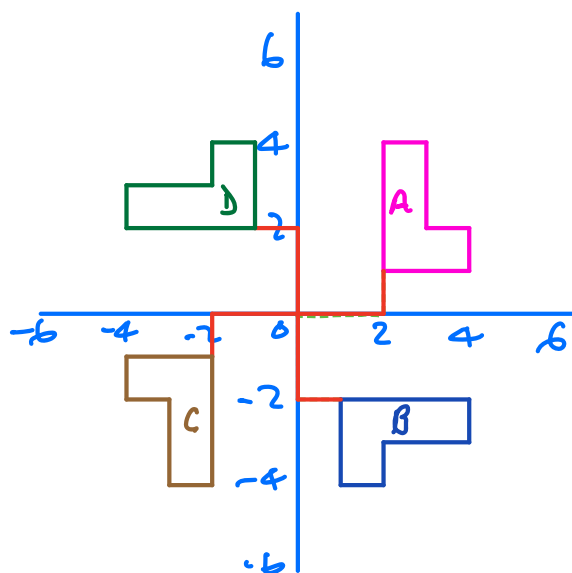
Vertical lines become horizontal

Horizontal lines become vertical



Example 2

Rotations

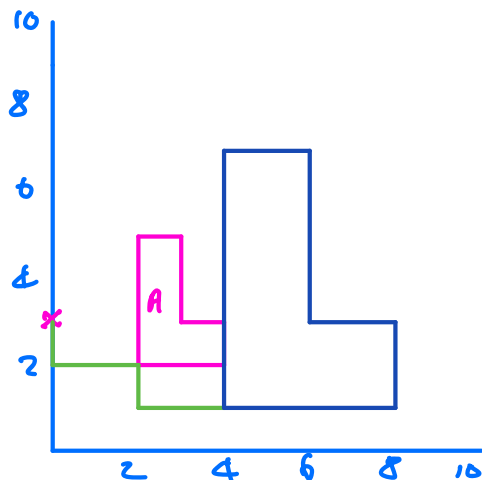


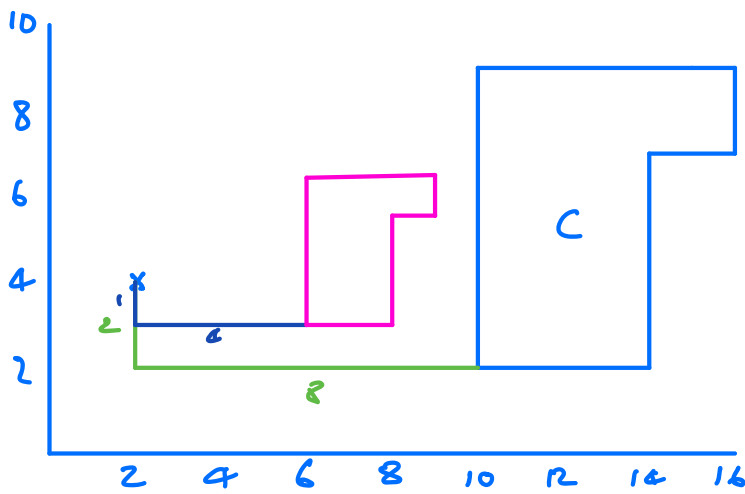
Rotate A 90° clockwise about $(0,0)$ to give B

A is mapped to C by a rotation of 180° about $(0,0)$

Enlargements

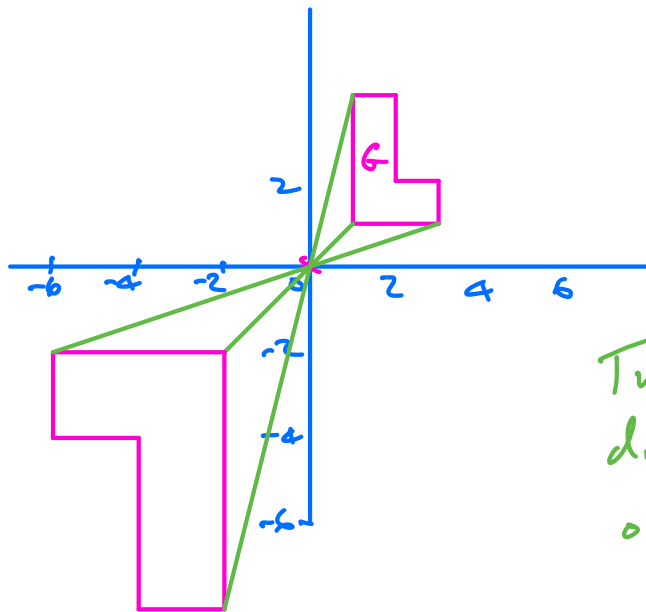
Enlarge A by scale factor 2 about centre of enlargement $(0,3)$





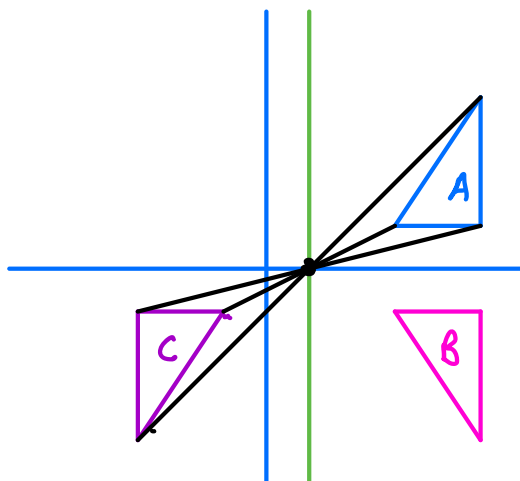
Enlarge C
by scale factor $\frac{1}{2}$
about (2,4)

Negative Scale Factors



Enlarge G by
scale factor -2
about (0,0)

Twice as far in opposite
direction from centre
of enlargement



Rotation by 180°
about (1,0)

OR

Enlargement by
scale factor -1
about (1,0)